

Analysis of control factors and surface integrity during wire-EDM of Inconel 718 alloy using T-GRA approach

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Abstract

In today's competitive modern manufacturing sectors, there is a vital need of utter precision and rigorous processing using various manufacturing approaches that directly influences the cost and processing duration of mechanized materials in addition to the consistency of the finished products. Therefore, it's essential to figure out the required output by adjusting the control factors of any machining techniques which resulted in optimal values of the desired outcome. In this study, machining evaluation and process optimization is carried out on volumetric extraction of material namely material removal rate (MRR), kerf obtained during the machining (K_w) and surface roughness (SR) of Inconel 718 superalloy during CNC controlled wire- electrical discharge machining. Four controllable factors- pulse interval, wire speed, pulse duration and peak current are considered to investigate the influence on performance measures. Taguchi's L_{16} has been used to construct the set of experiments before physical experimental runs and most influencing factors have been evaluated using ANOVA. SEM images and EDXS analysis have been resorted to examine the morphology of Inconel 718. These findings assist in identifying the topography of the machined surface. Further, the optimum integration has been obtained for the best yield and recorded using grey relational analysis integrated with Taguchi's technique (T-GRA). The unfamiliarity of the work is based on consideration of zinc coated thin wire electrode and Taguchi-Grey combined approach of modelling with four levels of experimental design.

Keywords: Wire-EDM, Inconel 718, ANOVA, T-GRA, Scanning Electron Microscopy

1. INTRODUCTION

Recently, technology based advancement has provided an opportunity for new industrial materials with properties that allow them to be used under harsh operating conditions, which include high temperatures, hostile

chemical environments, variable loads and others. This type of conditions exist in industrial gas turbines, nuclear power stations, space industry, submarines, equipment for power generators or installations in the chemical industry. Among Ni- Cr based alloys, Inconel 718 is widely used in the manufacturing of industrial turbine engine subsystems which includes blades, combustors and shells; nuclear stations equipment such as reactors and pumps; aircraft and submarines structural equipment; medical devices; dies, casing and heat treating tools [1], [2]. However, Inconel 718 constitute a significant hindrance during conventional machining operations owing to its thermal conductivity, higher work hardening properties, occurrence of abrasives in superalloy, hot-hardness, chemical affection to tool materials and built-up edge formations etc. [3]–[8] Therefore, non-conventional machining operations are preferred.

2. RELATED WORKS

Wire-EDM is among the quite important and often used non-conventional thermoelectric technique in the manufacturing sectors due to its ability to create three dimensional complex shape and geometry using bare or coated thin wires [9]–[11]. In the literature, the performance and behaviour of wire-EDM for emerging materials are well established. In general, wire-EDM's machining efficiency is predominantly affected by a combination of characteristics of wire electrode, properties of material, pulse generator system, machine automation system and dielectric fluid flushing technique. Various scientific research and studies have been recorded in the last decades on the machining of materials such as alloys, superalloys and composites using wire-EDM, but limited data available concerning the wire-EDM of Inconel 718 with thin coated wire electrode. The impact of new form of Cu-SiC electrode for wire-EDM investigated [12] and examine the efficiency of material removal and the surface finishing, among others. As a result, the cutting efficiency increased by 16 percent while roughness (R_a) decreased by around 17 percent on an average. The effect of the control factors of wire-EDM on micro-hardened machined surface of Inconel 617 were examined [13], and stated that many visible micro-cracks developed with increase in current and pulse duration. Simultaneously, the micro-hardness also increases. The effects of surface quality versus discharge energy are presented [14] and SR for parallel and perpendicular wire directions is shown to be similar and by reducing the discharge energy, its average result can be considerably lowered. The surface structure was compared and recorded white layers and non-uniform confined micro voids with higher discharge energy. Experimental analysis carried out to examine the significant factor in wire-EDM that led to the existence of thick recast layer with 5 to 9 μm thickness in Inconel superalloys [15]. Some findings concerning the effect of machining methods on surface morphology and stereo-metric surface parameters in wire-EDM of hard machined materials which also include Inconel alloys, are discussed [16]. Simultaneously, several

studies can be reported in literature that discusses the challenges correlated with precision machining of different materials with wire-EDM [17]. The findings of magnesium alloy in view of efficient machining operation with different facets of the performance and reliability of the magnesium alloy are discussed using wire-EDM [18], [19]. The findings of an experimental study on the selection of processing conditions that decide performance of wire-EDM using aluminium alloy and the optimization abilities of some output responses in wire-EDM of reinforced ZC63 metal matrix composite are discussed [20], [21]. Experimental investigation of performance measures using wire-EDM for aluminium alloy-7017 and rolled homogeneous armor (RHA) steel shows favourable value [22]. The multi-response optimization of control factors has been extended further [23]–[25].

3. ORIGINALITY

It is clear from the literature report that very less investigation carried out in the machining of Inconel 718 using zn-coated brass wire. In wire-EDM technique, MRR, K_w and SR are major aspects regarding the performance improvement. Therefore, multi-response optimization has been executed for selected performance measures.

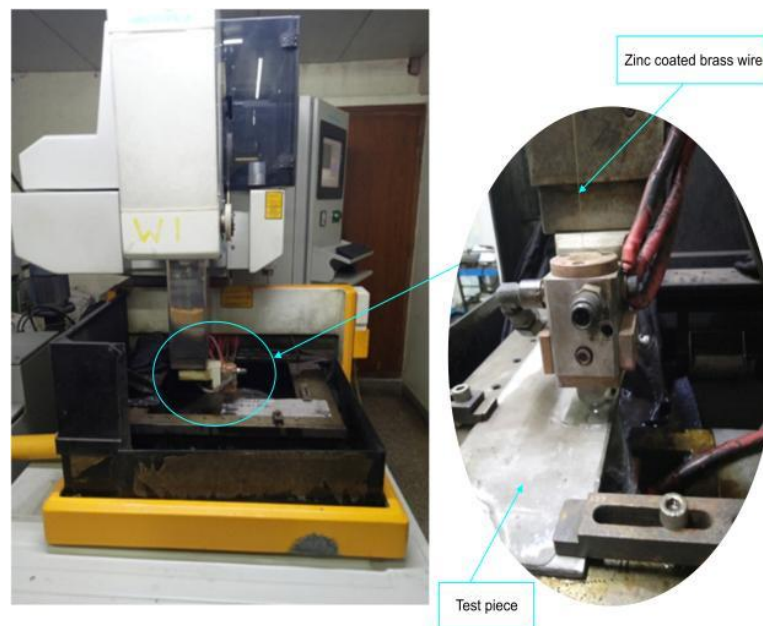


Figure 1. CNC controlled wire EDM experimental setup

The primary objective of this study is to evaluate the impact of control factors in wire-EDM of Inconel 718 material and to identify the optimal condition by adjusting the factors using T-GRA approach for performance gains. Further, SEM images and EDXS analysis have been resorted to examine the surface morphology of Inconel 718. This finding assists in identifying the micro-structure changes, material transfer, and compound formation after the machining process.

4. SYSTEM DESIGN

4.1 Equipments setup and measurement

In an attempt to conduct the experimental test, Electronica Sprintcut (Elpuls 40) wire electric discharge machine is used in which axial motion in Z-axis, Y-axis and X-axis is controlled by computerized numerically controlled (CNC) mechanism as depicted, Figure 1. A cylindrical coated brass wire with diameter of 0.25 millimetres has handled as an electrode in this analysis. A plate made from a nickel-chromium alloy Inconel 718 (certified by Spectro Analytical Labs Ltd, Greater Noida, India) is considered as a test piece for the experimental study whose mechanical properties and percentage of elements (determined using IS-228-1987/SOP-CHE-00-XRF Spectrometer/SOP-CHE-00-ICP test method) are arranged and depicted in Table 1 and Table 2.

Table 1. Attributes of Inconel 718

Mechanical /Physical attribute	Count	Units
Hardness	84.6	HRB
Density	8.2	gm/CC
Melting Range	1260-1330	°C

Table 2. Percentage composition of Inconel 718

Elements	Nickel	Chromium	Niobium	Molybdenum	Titanium
Symbol	Ni	Cr	Nb	Mo	Ti
Weight %	52.91	18.29	4.79	2.82	0.9
Elements	Silicon	Manganese	Cobalt	Carbon	Phosphorus
Symbol	Si	Mn	Co	C	P
Weight %	0.22	0.2	0.2	0.06	0.01

Initially, the material was a rectangular plate and cut into the pieces of 15 x 15 x 5 (millimetre). Due to comparatively good dielectric strength [26], de-ionized water is exploited as a dielectric liquid in this study. Dielectric flow rate is considered as a noise factor in this experimental analysis.

4.2 Design of Experiments (DOE) and factors

A mathematical modelling and statistical approach for organizing the correlation among the various other variables influencing a process is known as DOE. With the aim to achieve the optimum conditions, DOE is an approach that restricts the number of experiments for conducting the test. This investigation is concerned with experimental design, and planned according to L₁₆ orthogonal array design of experiments in order to obtain the results using Minitab^(R)-16.1.1 software. Four controllable factors were selected (four levels for each factor) to conduct sixteen experiments with two repeats and then taking their average to get the final count of performance measures.

The most efficient use of the wire-EDM requires careful selection of machine settings. Wire-EDM is a complex system that may be influenced by a wide range of characteristics and other variables. However, Pulse duration,

pulse interval, peak current and wire speed are most influencing control factors in getting higher accuracy with minimum cost. Peak current is a term used to characterize the maximum current generated during cutting. The discharge energy grows proportionally to the peak current and it grows till the predetermined limit with each pulse time. MRR will be improved with higher currents, but surface quality will be sacrificed. The selected variable factors with their levels are depicted in Table 3. The variations in the value of control factors have been decided as consequences of literature, trial runs and considering the other constraint of wire-EDM to avoid the wire breakage and obtrusion of the machining process.

Table 3. Variable control factor with levels

Factors	Units	Notations	Levels			
			1	2	3	4
Pulse duration	μs	T _{on}	104	107	110	113
Pulse interval	μs	T _{off}	50	52	54	56
Peak Current	A	I _p	10	11	12	13
Wire Speed	m/min	U _w	1	2	3	4

Other factors that could influence the performance measures are tabulated and shown in Table 4 and were kept invariable throughout the all sixteen experiments.

Table 4. Invariable machining factor in experiment

Constant factor	Value	Unit
Dielectric fluid	De-ionized water	-----
Dielectric temperature	21±1	°C
Wire Tension	9	N
Servo voltage	20	V
Diameter of wire	0.25	Mm
Electrode material	Zn coated brass wire	-----
Servo feed	2100	Machine unit

MRR can be estimated as the fraction of volumetric depletion of the test piece to the processing time. The estimation of volumetric reduction of the test piece can be defined using mass-density relation. Therefore, the MRR is calculated using loss in mass criteria function and can be measured by Equation 1:

$$MRR = \frac{\text{mass reduction in test piece (gm)}}{\text{density of workpiece } \left(\frac{\text{gm}}{\text{mm}^3}\right) \times \text{processing time (min)}} \quad (1)$$

After each run of experiments, the test piece were weighted prior to the machining on a digital weighing balance machine to calculate the mass reduction and used stopwatch to measure the processing time. The value of Kw was estimated using digital microscope and observed at three locations and then average of measured value was taken for analysis. With the aim to check the SR, measurement of central line average (Ra) were used and measured by using roughness tester ZEISS & ACCT, SURFCOM FLEX-50A.

The scanning electron microscopy (SEM) was used to get the microscopic impressions of selected surfaces and energy dispersive x-ray spectroscopy (EDXS) were also conducted to figure out the presence of elements and phases of machined surface.

4.3 GRA

The grey relational analysis (GRA) has been practised to optimize the multiple performances. It provides a functional solution to the complexity, multiple inputs and isolated data problems based on grey theory [27]. Since the wire-EDM process is of a multi-faceted nature, the GRA is therefore adopted for the multi-response optimization to optimize the performance measures. Grey theory imparts complete information and represents the known data by black, while insufficient and unidentified information are characterized by white. Grey relation denotes discrete, insufficient, and unpredicted data, and grey relational theory denotes a relationship with complete details and information. The steps involved in GRA [28] shown through flowchart depicted in Figure 2.

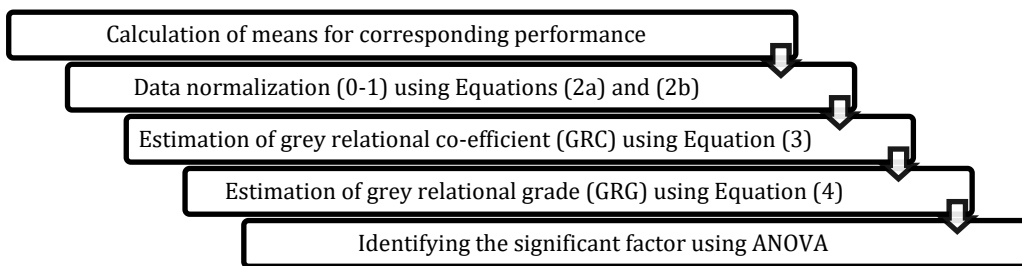


Figure 2. Flowchart involved in GRA

Higher the better for calculation of MRR

$$z_i^*(k) = \frac{z_i^o(k) - \min z_i^o(k)}{\max z_i^o(k) - \min z_i^o(k)} \tag{2a}$$

Lower the better for calculation of Kw and SR.

$$z_i^*(k) = \frac{\max z_i^o(k) - z_i^o(k)}{\max z_i^o(k) - \min z_i^o(k)} \tag{2b}$$

Where $z_i^*(k)$ is the measured string, $z_i^o(k)$ is the row string, where $\max z_i^o(k)$ is the larger count of $z_i^o(k)$, $\min z_i^o(k)$ is the smaller count of $z_i^o(k)$ with $i=1,2,\dots,m$ and $k=1,2,\dots,n$ with $m=16$ and $n=3$,

To understand the interaction between best and mean values, the GRC is calculated as follows:

$$\mathcal{E}(k) = \frac{\Delta \min + \delta \Delta \max}{\Delta oi(k) + \delta \Delta \max} \tag{3}$$

Where $\Delta oi(k)$ shows the deviation sequence from normalized data from unity and can be calculated as:

$$\Delta oi(k) = |1 - z_i^*(k)|, \delta \text{ is the distinguishing co-efficient and usually taken as } 0.5.$$

The GRG is determined using the following equation by assigning equal weight to all performance measures:

$$GRG = 1/n \sum_{k=1}^n \mathcal{E}(k) \tag{4}$$

Where \mathcal{E} is the respective GRC for the performance measures.

5. EXPERIMENT AND ANALYSIS

The investigational performance central value and signal to noise (S/N) ratio of MRR, K_w and SR correspond to all sixteen experimental runs are depicted in Table 5.

Table 5. Experimental value of process performance using L_{16} OA with four factors

Ex p. No.	T_{on} (μs)	T_{off} (μs)	I_p (A)	U_w (m/m in)	MRR (mm^3/min)	K_w (mm)	SR (μm)	S/N MRR	S/N K_w	S/N SR
1	1	1	1	1	1.092	0.317	0.423	0.764	9.979	7.473
2	1	2	2	2	1.842	0.322	0.481	5.306	9.843	6.357
3	1	3	3	3	2.047	0.357	0.471	6.222	8.947	6.540
4	1	4	4	4	2.745	0.398	0.481	8.771	8.002	6.357
5	2	1	2	3	1.877	0.350	0.587	5.469	9.119	4.627
6	2	2	1	4	1.556	0.368	0.537	3.840	8.683	5.401
7	2	3	4	1	2.290	0.358	0.542	7.197	8.922	5.320
8	2	4	3	2	2.477	0.375	0.546	7.879	8.519	5.256
9	3	1	3	4	2.694	0.376	0.721	8.608	8.496	2.841
10	3	2	4	3	2.616	0.372	0.696	8.353	8.589	3.148
11	3	3	1	2	1.630	0.349	0.627	4.244	9.143	4.055
12	3	4	2	1	2.420	0.375	0.584	7.676	8.519	4.672
13	4	1	4	2	2.925	0.365	0.802	9.323	8.754	1.917
14	4	2	3	1	2.797	0.357	0.717	8.934	8.947	2.890
15	4	3	2	4	3.073	0.402	0.692	9.751	7.915	3.198
16	4	4	1	3	2.532	0.411	0.671	8.069	7.723	3.466

5.1 Evaluation of MRR

With the aim of examine the influence of control factors, an ANOVA has been conducted and results corresponding to MRR depicted in Table 6.

Table 6. ANOVA for MRR

Source	*DF	*Seq SS	*Adj SS	*Adj MS	*F	*P	%
Ton	3	1.92842	1.92842	0.642805	72.85	0.003	41.02
Toff	3	0.37285	0.37285	0.124283	14.08	0.028	7.93
Ip	3	2.06528	2.06528	0.688425	78.02	0.002	43.94
Uw	3	0.30714	0.30714	0.102379	11.60	0.037	5.63
Residual Errors	3	0.02647	0.02647	0.008824			
Total	15	4.70015					

S = 0.09394 R-Sq = 99.4% R-Sq(adj) = 97.2%

*DF - Degree of freedom; Seq. SS - Sum of Squares (Sequential); Adj MS - Mean Square (Adjusted); F - F value (At 95% confidence interval); p - p value.

The results from ANOVA interpreted that peak current is the most influencing factor accounting for 43.94% of the contribution, followed by pulse duration. The pulse interval and wire speed is less influencing factors for extraction of material from the surface. Figure 3 shows graphs depicting

the impact of control factors on MRR with response values, which indicate that higher material extraction from the surface with increase in peak current, pulse duration and pulse interval. This may be for the reason that as peak current rises, the discharge energy from the spark generated amongst the wire electrode and the test piece rises as well. This energy raises the temperature, which contribute to higher extraction of material from surface.

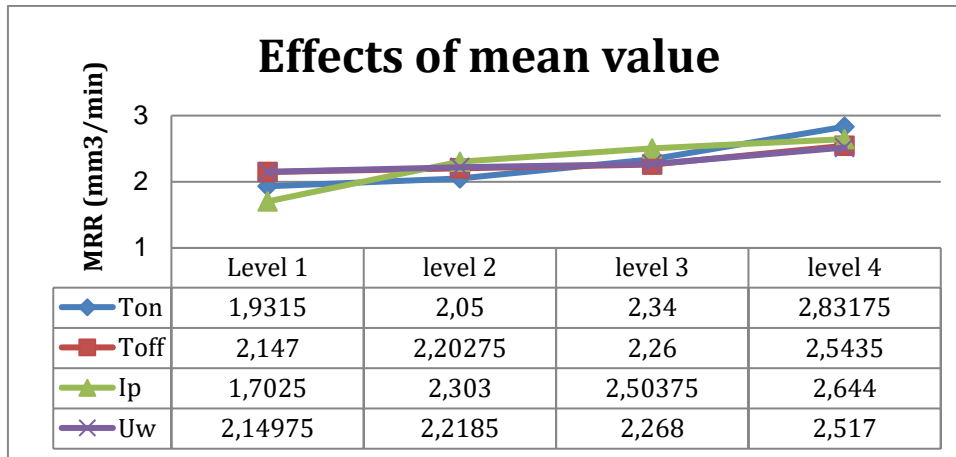


Figure 3. Effect of selected control factors at different levels for MRR

Graph also depicts that corresponding value of MRR increases with the levels of pulse duration and interval. This may be for the reason that considerable amount of heat energy generated between wire electrode and test piece due to higher spark, which leads to faster erosion contributes to higher material removal [29], [30].

5.2 Evaluation of Kw

In order to examine the influence of control factors, an ANOVA analysis has been conducted and results corresponding to Kw depicted in Table 7.

Table 7. ANOVA for Kw

Source	DF	Seq SS	Adj SS	Adj MS	F	P	%
Ton	3	0.002543	0.002543	0.000848	92.45	0.002	26.06
Toff	3	0.003547	0.003547	0.001182	128.96	0.001	36.36
Ip	3	0.000356	0.000356	0.000119	12.95	0.032	3.64
Uw	3	0.003283	0.003283	0.001094	119.36	0.001	33.65
Residual Errors	3	0.000028	0.000028	0.000009			
Total	15	0.009755					

S = 0.003028 R-Sq = 99.7% R-Sq(adj) = 98.6%

The results from ANOVA interpreted that pulse interval is the uttermost influencing factor accounting for 36.36% of the contribution, followed by wire speed and pulse duration. Figure 4 illustrates graphs depicting the impact of control factors on Kw with response values, which indicate that Kw increases with increase in current, pulse duration and pulse interval as well. This may be for the reason that increased pulse duration leads to longer

spark and large ionization incorporation with dielectric fluid, causes higher chips removal from the surface. As a result, the width increases in accordance with the chips removal from the surface. Graph also indicate that the value of K_w increases with levels of peak current for the reason that increased intensity of spark attributes to high spark energy generation caused by quantum electrons discharged from wire hitting with the dielectric fluid contributing in large ionization [31], [32]. High intensity spark and large ionization causes the widening of the kerf when considerable amount of ions strike with the test piece.

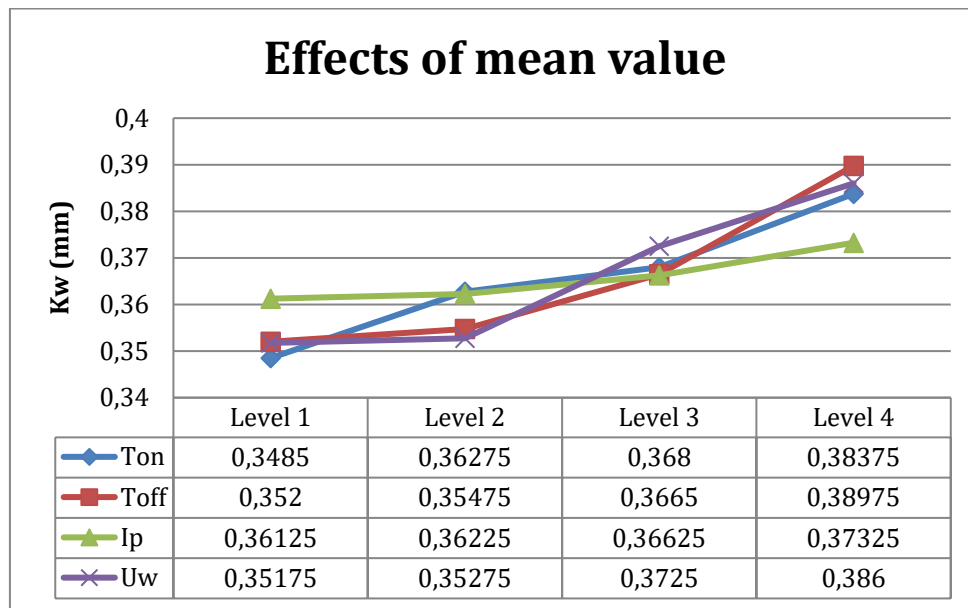


Figure 4. Effect of selected control factors at different levels for K_w

5.3 Evaluation of SR

The quality of finished surface depends on variety of the mechanical and physical characteristics of the test surface particularly, resistance to corrosion, friction, fatigue stability, and loading competency [19], [31]. Thus, the quality of surface obtained throughout the machining of test piece is interpreted by the average roughness height (Ra) and termed as surface roughness (SR). Roughness is nothing but the existence of hollows and irregular debris on finished surface as a result of spark discharges. In an effort to examine the influence of control factors, an ANOVA analysis has been conducted and results corresponding to SR depicted in Table 8. The results from ANOVA interpreted that pulse duration is the uttermost influencing factor accounting for 85.71% of contribution. Figure 5 illustrates graphs depicting the impact of control factors on SR with response values, which indicate that surface quality deteriorate with increasing in pulse duration and peak current while improves with rise in pulse interval.

Table 8. ANOVA for SR

Source	DF	Seq SS	Adj SS	Adj MS	F	P	%
Ton	3	0.153867	0.153867	0.051289	288.55	0.000	85.71
Toff	3	0.009269	0.009269	0.003090	17.38	0.021	5.16
Ip	3	0.010211	0.010211	0.003404	19.15	0.018	5.68
Uw	3	0.005639	0.005639	0.001880	10.58	0.042	3.14
Residual Errors	3	0.000533	0.000533	0.000178			
Total	15	0.179520					

S = 0.01333 R-Sq = 99.7% R-Sq(adj) = 98.5%

This may be for the reason that enough spark energy creates larger current intensity causes higher material erosion from the surface layers. The ionized particles that form, erupt and eject the material from the work surface after each pulse duration, forming wide and deep craters. The surface irregularities due to these craters lead to increase SR and also attributed that augmentation of plasma channel with rise in pulse duration [33], [34].

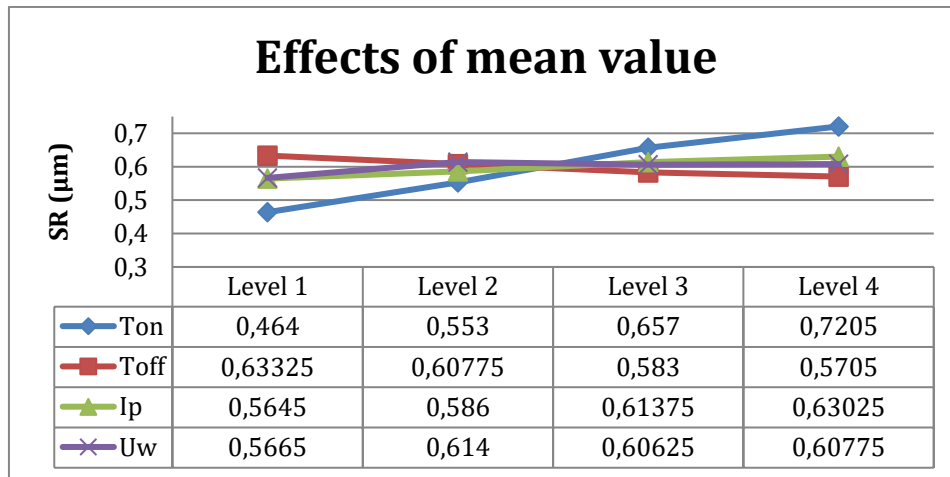


Figure 5. Effect of selected control factors at different level for SR

5.4 Microstructure Characterization of Surface

The EDM surface is usually tarnish in nature, consisting of a re-solidified layers, craters, pockmarks, globules, debris, droplets and other layers.

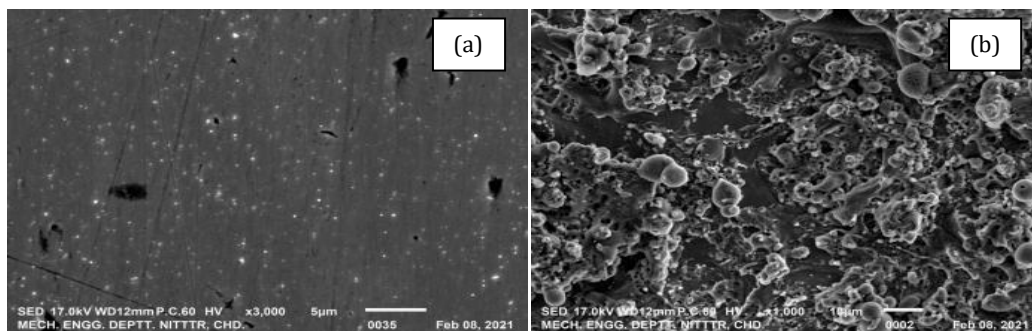


Figure 6. SEM micrograph of Inconel 718 (a) received material (b) after machining with wire EDM

SEM analysis has been done in this study to check and evaluate the microstructure characteristics of the machined surface with different range of measurement. Figure 6(a) depicts image of the surface before the machining and Figure 6(b) after machining of Inconel 718 with wire-EDM. The surface consists of spherical grains separated from test piece which cannot be flushed out from the surface with dielectric pressure, globules of debris that melts and stick to the surface, deposits and randomly distributed craters of different sizes. These craters are nothing but a void and cavities, created by spherical chips that have broken away from the surface due to the impact of spark in between test piece and wire electrode during the machining. Owing to the release of trapped gases during the solidification, pockmarks appeared on the machined surface. Molten debris solidifies and spread as globules on the machined surface due to surface tension [35]. The SEM images of the test piece which were showing highest MRR ($T_{on}=113 \mu s$, $T_{off}=54 \mu s$, $I_p=11 A$, $U_w=4 m/min$) depicted in Figure 7 (a) and 7 (b), lowest SR and K_w ($T_{on}=104 \mu s$, $T_{off}=50 \mu s$, $I_p=10 A$, $U_w=1 m/min$) depicted in Figure 8(a) and 8(b).

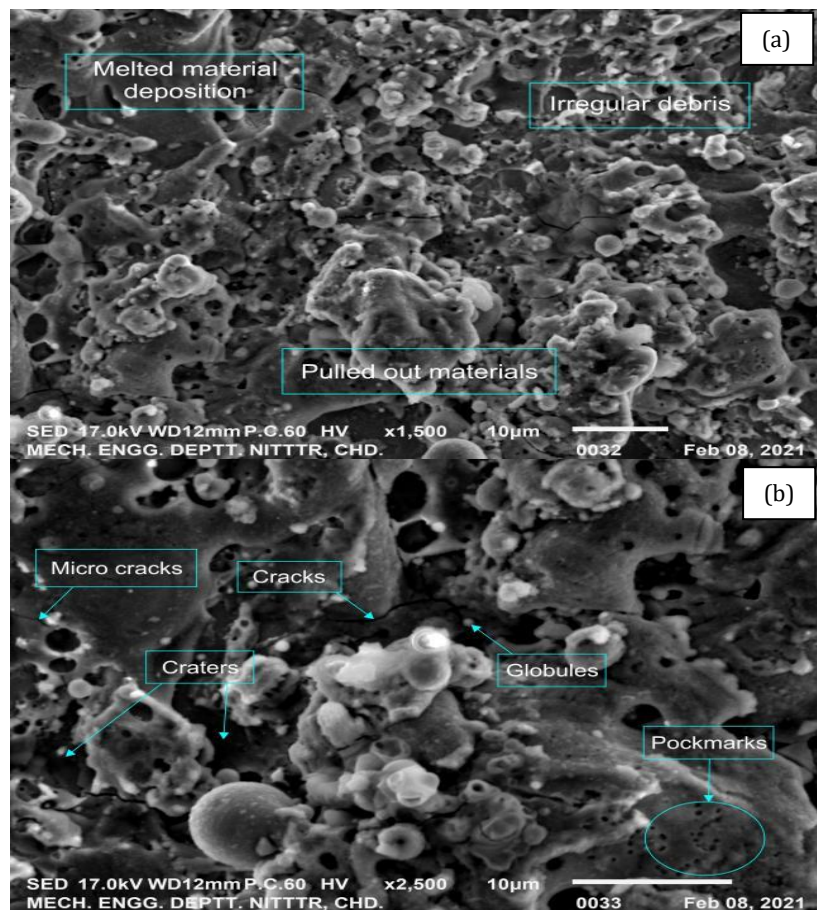


Figure 7. SEM micrographs of machined surface during wire EDM for MRR ($T_{on}=113 \mu s$, $T_{off}=54 \mu s$, $I_p=11 A$, $U_w=4 m/min$) showing (a) material deposition (b) pockmarks and craters

It was perceived that at the highest value of MRR ($3.073 \text{ mm}^3/\text{min}$), wide and deep craters have developed because of higher pulse duration ($113 \mu\text{s}$) and peak current (11 A), depicted in Figure 7. This may be for the reason that higher pulse duration results in high discharge energy which leads to the flow of heat towards the surface, resulting in higher dissipation of materials from the surface, leading to a large number of pockmarks, debris, and craters [36]. During machining, de-ionized water flushes out some of the molten material and looks in a pulled-out shape on the machined surface. The remaining materials re-solidified in the form of uneven or irregular debris. However, the surface had fewer craters, micro-cracks, and some visible pockmarks when the minimum SR of experimental run 1 was evaluated using the SEM depicted in Figure 8. This may be for the reason that when peak current is low, less intense heat transfer towards the surface and lower spark generation causes the less material extraction from the test piece that improves the surface smoothness and lowers the K_w as well [23], [37], [38].

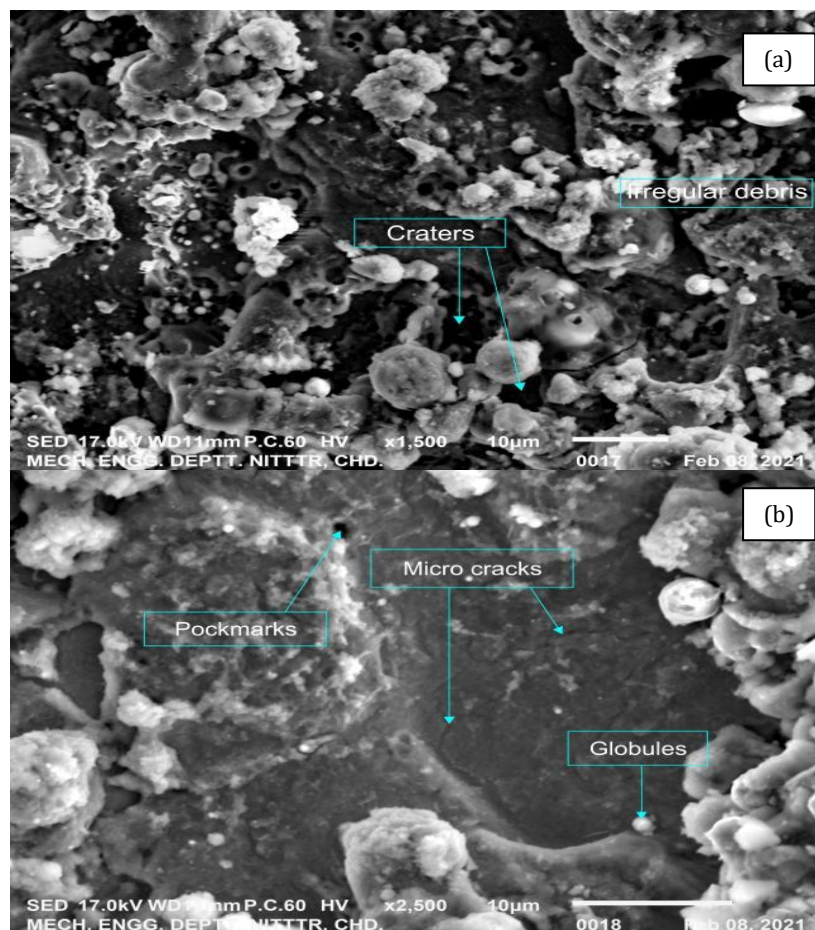


Figure 8. SEM micrographs of machined surface during wire EDM for SR and K_w ($T_{on}=104 \mu\text{s}$, $T_{off}=50 \mu\text{s}$, $I_p=10 \text{ A}$, $U_w=1 \text{ m/min}$) showing (a) Irregular debris (b) micro-cracks and globules

The occurrence of elements on the surface of test piece analysed using EDXS analysis depicted in Figure 9(a) and 9(b), perceived that some other elements are appear on the test piece's surface apart from elements present before machining. This may be due to transfer of materials from wire electrode and dielectric fluid. Elements also appeared from the debris deposited at the surface in compounded phase.

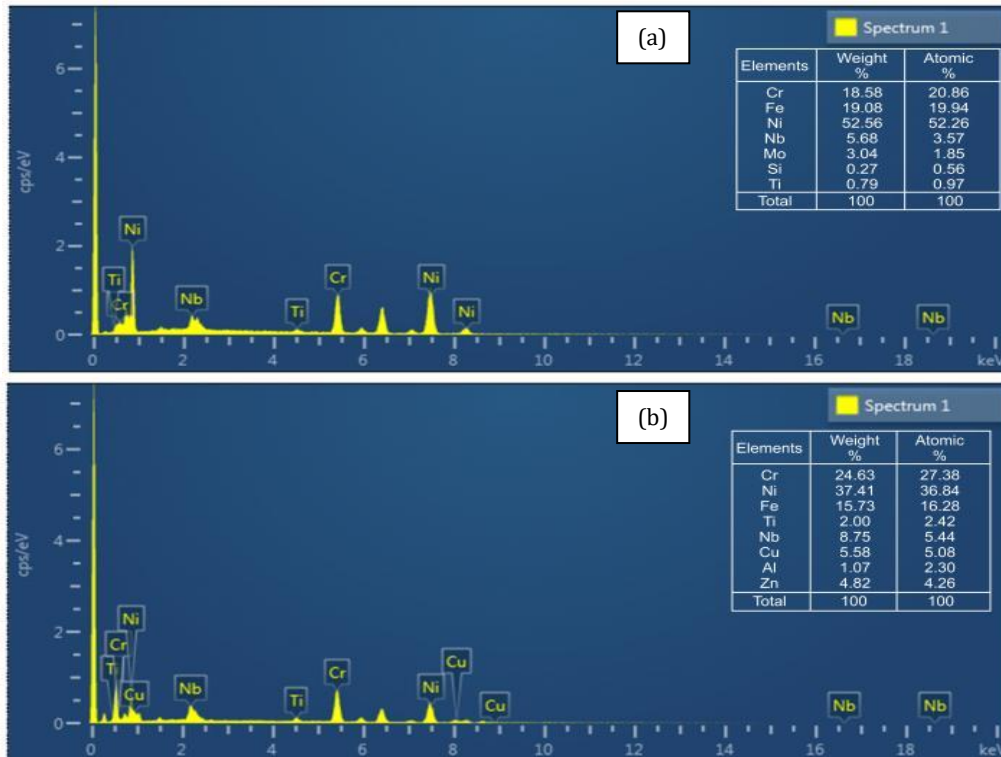


Figure 9. EDXS elemental spectrum with composition of (a) received material (b) machined surface obtained

The analysis also revealed that large number of elements transferred to surface of test piece from the wire electrode. Cu (Copper), Zn (Zinc) and Al (Aluminium) were located in the EDXS spectrum, suggesting that a large volume of these elements have relocated to the test piece's surface caused by decomposition of deionised water and re-solidification of electrode material at high temperature. Transfer of elements is depending on pulse duration and peak current.

5.5 MULTI-RESPONSE OPTIMIZATION USING T-GRA

The values of GRC and GRG for each performance measures are arranged in Table 9. GRG values are considered as the single performance and are optimized using the Taguchi's technique in Minitab^(R)-16.1.1. For all experimental runs, the experiment with the maximum GRG value is considered to be the best option (out of 16 experimental run). The ranks were assigned in accordance with ascending GRG values.

Table 9. Normalized data and values of GRC and GRG of each performance

Exp. No.	Normalized values			GRC			GRG	Rank
	MRR	Kw	SR	MRR	Kw	SR		
1	0.000	1.000	1.000	0.333	1.000	1.000	0.778	1
2	0.379	0.947	0.847	0.446	0.904	0.766	0.705	2
3	0.482	0.574	0.873	0.491	0.540	0.798	0.610	4
4	0.834	0.138	0.847	0.751	0.367	0.766	0.628	3
5	0.396	0.649	0.567	0.453	0.588	0.536	0.526	11
6	0.234	0.457	0.699	0.395	0.480	0.624	0.500	14
7	0.605	0.564	0.686	0.559	0.534	0.614	0.569	7
8	0.699	0.383	0.675	0.624	0.448	0.606	0.559	9
9	0.809	0.372	0.214	0.723	0.443	0.389	0.518	12
10	0.769	0.415	0.280	0.684	0.461	0.410	0.518	13
11	0.272	0.660	0.462	0.407	0.595	0.482	0.495	15
12	0.670	0.383	0.575	0.603	0.448	0.541	0.530	10
13	0.925	0.489	0.000	0.870	0.495	0.333	0.566	8
14	0.861	0.574	0.224	0.782	0.540	0.392	0.571	6
15	1.000	0.096	0.290	1.000	0.356	0.413	0.590	5
16	0.727	0.000	0.346	0.647	0.333	0.433	0.471	16

Experiment number 1 has the maximum GRG value of 0.788 and is graded first with foremost values of MRR as 1.092 mm³/min; Kw as 0.317 mm; and SR as 0.423 μm. Table 10 depicts the GRG response values for each factor along with their levels. Every response characteristic's optimum value is predicted using the impact of significant factors. The response variable values must lie in 95 % confidence interval, as determined by CI_{CE} validation experiments.

Table 10. Response table for GRG

Factors	Levels				Delta	Rank
	1	2	3	4		
T _{on}	0.6802	0.5384	0.5154	0.5496	0.1648	1
T _{off}	0.5969	0.5736	0.5658	0.5472	0.0497	3
I _p	0.5608	0.5877	0.5648	0.5703	0.0269	4
U _w	0.6121	0.5813	0.5312	0.5590	0.0810	2

The predicted GRG is computed by utilising Equation 5:

$$\mu = \mu_r + \sum_{i=1}^n (\mu_i - \mu_r) \quad (5)$$

μ_r is average score of GRG, μ_i is average score of GRG at optimum level, and n control factors. Optimum values were predicted using equation and response values in a similar way to GRG.

5.6 Confirmation test

After predicting the optimum levels of control factors of the wire-EDM through analysis, the next effort is to confirm and substantiate the performance results using predicted values. Accordingly, the confirmation test had performed for the performance outcomes. The outcomes of the confirmatory tests are correlated with initial levels of the control factors.

Table 11 depicts the outcomes of confirmation run for the performance measures. Two confirmation tests were effectuated to validate the performance characteristics obtained at utmost levels of control factors.

Table 11. Confirmatory experimental results

Process Setting	Initial optimized (6 th experimental run)	Optimum value using T-GRA		Percentage Improvement
		Predicted Value	Confirmatory Value	
Optimum condition	$T_{on}=107,$ $T_{off}=52, I_p=10,$ $U_w=4$	$T_{on}=104,$ $T_{off}=50, I_p=11,$ $U_w=1$	$T_{on}=104,$ $T_{off}=50, I_p=11,$ $U_w=1$	
MRR	1.556	1.666	1.993	19.62
K_w	0.368	0.317	0.309	2.52
SR	0.530	0.453	0.392	13.46
GRG	0.518	0.763	-----	-----

The estimated value and mean value of MRR, K_w and SR acquired through the confirmation test were evaluated and compared with the 6th experimental run from the experimental plan.

6. CONCLUSION

The study focuses on predicting the optimal values by adjusting the control factors of wire-EDM using Taguchi's and GRA combined approach. At first, experiments were designed using the Taguchi technique. The GRA technique converts the various values and measurements into a standard scale to obtain a single count. This count will now be useful in evaluating and assessing the multi response optimization results. The outcomes of the T-GRA approach has suggested that pulse duration (104 μ s, level 1) pulse interval (50 μ s, level 1) peak current (11 A, level 2) wire speed (1 m/min, level 1) exhibits the exemplary combination of control factors. Conclusively, confirmatory findings revealed that material removal rate enhanced by 19.62%, improvement in kerf width by 2.52% and improvement in surface roughness by 13.46%. Beside this there are some other conclusions drawn based on the findings of the experiments:

1. Peak current and pulse duration had an expressive influence on MRR. Peak current is found to be the most encouraging factor, providing 43.94 percent to MRR followed by pulse duration.

2. The pulse interval and wire speed showed expressive contribution on K_w . These significant factors should have lower levels to achieve the lower kerf.

3. With a contribution of 85.71 percent, pulse duration has a vital significance on the SR. The lower levels of pulse duration desired to attain a better surface characteristic.

4. SEM and EDXS were used to investigate the micro-structure changes, material transfer, and compound formation after machining process. SEM analysis revealed the presence of overspreading craters, several pockmarks

of varying sizes, and diminutive cracks in the test piece. The EDXS findings confirmed the main contribution of Iron (Fe), Niobium (Nb), Nickel (Ni), Chromium (Cr), and a minor amount of Zinc (Zn) that is transferred to the machined surface.

5. This work can provide future experimenters and researchers with a practical guide to choose the best control factor to acquire the desired MRR, K_w , and SR while using wire-EDM for Inconel 718 material.

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