

Wavelet Based Fault Detection and Classification Algorithm for a Real Distribution Feeder

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Abstract

As the importance of protection in power systems increase, knowing the type of malfunction occurring in the system has become crucial. Especially in the distribution system where electricity is delivered to the consumer, detecting the right fault type with a short amount of time is important. For this purpose in this study, Akyazı-Düzköy distribution feeder in Trabzon/Turkey, where faults commonly occur, is modeled with Digsilent Powerfactory. The model is performed with actual parameters including 465 lines, 243 loads, 233 transformers and 1093 busbars. First, the load flow and short circuit analysis have been carried out for the validation of the model. Then a fault detection and classification algorithm is enhanced using the wavelet transform and the energy of the coefficients. Different types of short circuit faults are created at different points on the model to test the accuracy of the algorithm. The fault inception time and the effect of the fault resistance are also investigated.

Keywords: Distribution System, Fault Detection, Digsilent Powerfactory, Wavelet Transform, Trabzon.

1. INTRODUCTION

Electrical energy has become indispensable in every area of our lives and for this reason, it should be provided with high quality. The quality of electrical energy depends on the continuity and reliability of the system. This will be possible by reducing the outage time and taking the right interventions with the detection of power system faults.

Many studies have been carried out in this area regarding the detection of fault and fault type. Adly and et al. [1] combined the merits of discrete wavelet transform (DWT) and Karen Bell Transformation for the fault analysis process. The proposed algorithm was tested on a 350km, 500kV transmission line using ATP/EMTP simulation package. Fault location, fault resistance, fault inception angle and different source capacities were validated using the algorithm. Affijulla and Tripathy [2] developed a robust fault detection and discrimination technique for transmission lines. The

algorithm was tested on IEEE 14-bus test system, six generator 23-bus system and the reduced NERES 25 bus Indian power system with PSS/Sincal software. The relay tripping decision was made with the fault detection and discrimination technique. Also, signal phasor estimation was carried out using the Hilbert Transform. Guillen and et al. [3] detected and classified faults in transmission lines based on DWT and singular value decomposition (SVD) using the current signals. Simulations were done in Digsilent Powerfactory using both WSCC 9 bus test system and own modeled system containing 4 busbars. The effect of fault impedance and inception time was also investigated. K-NN based fault detection and classification methods for power transmission systems were studied by Majd and et al [4]. Fault resistance, occurrence time, location, X/R ratio and phase angle effects were investigated in the simulations. In addition to these studies, fault detection in HV transmission lines[5], fault classification with Haar wavelet transform [6], wavelet-fuzzy combined approach for fault classification and location [7] and many others [8-10] can be found in the literature for transmission lines.

The studies have not only been limited to transmission lines but also a lot of work has been done on distribution lines [11-14]. Alves and Fonseca [15], have modeled a 282 non-transposed distribution feeder in ATP/EMTP software in order to detect faults by applying the discrete wavelet transform to the current signals. Ghaderi and et al. [16], studied a high impedance fault detection in the distribution network using the time-frequency-based algorithm. Oliveira and et al. [17], have enhanced a Fault classification in distribution systems based on fault current angles. The algorithm is based on Artificial neural networks associated with fault current angles information and classifies series, shunt and simultaneous faults with cable on the source or on the load. The proposed scheme was tested on IEEE 13 and 34-bus test system.

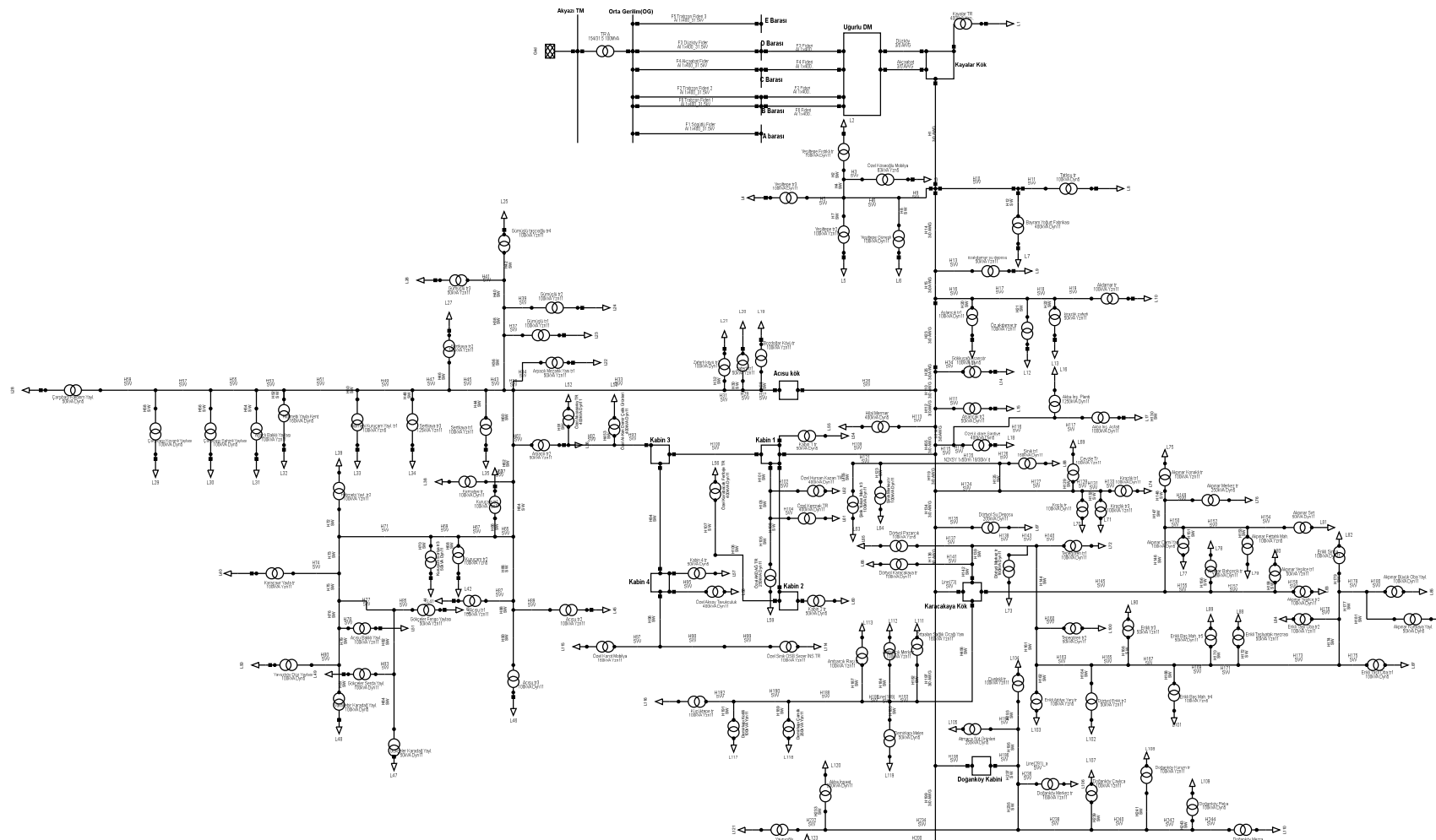
The aforementioned studies are mostly for test systems, not for real distribution feeders. In real distribution systems, it is difficult to detect the occurred faults especially for long-distance distribution lines with a branched structure in the rural area. In this study, a real distribution feeder containing 465 lines, 243 loads, 233 transformers and 1093 busbars is modeled in Digsilent Power Factory. The reliability of the model is investigated with load flow and short circuit analysis and satisfying result have been attained. For fault detection and classification, a wavelet transform and a Clarke transformation based algorithm is developed using the model current signals. Different types of faults are created at different locations in order to validate the proposed algorithm. Fault resistance and fault inception time are also investigated in the study. Compared to other studies, this study will contribute to the literature in terms of developing a fault detection algorithm by using current signals obtained from a real distribution feeder model with high reality.

2. SYSTEM MODELING

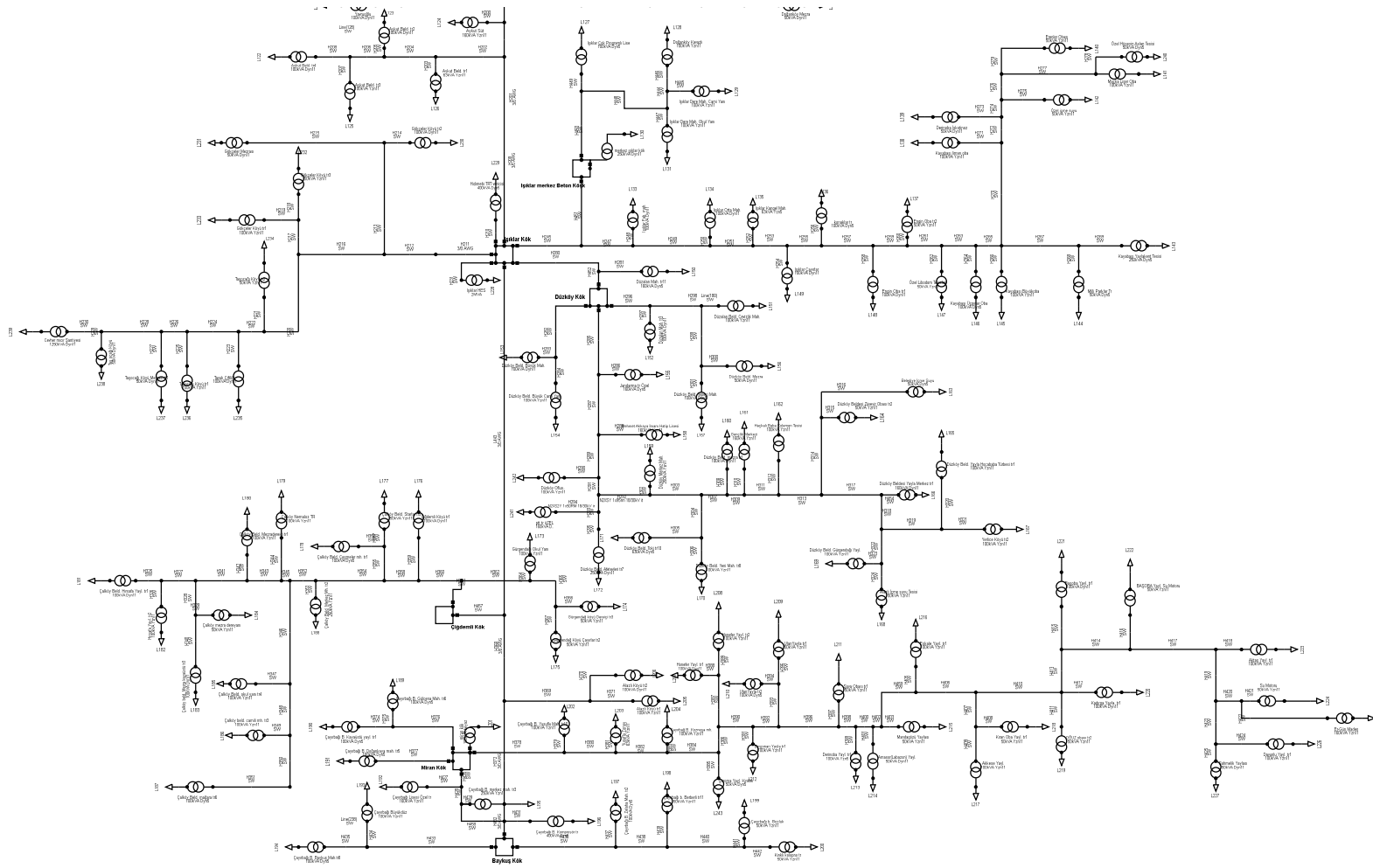
2.1. Modeling Real Distribution Feeder Located in Trabzon/Turkey

It is important in terms of system reliability and continuity to predict the consequences of failures in electrical networks. In this regard, network analysis programs provide an important convenience. Digsilent Powerfactory program is one of these analysis programs and the network modeling can be done as well as load flow analysis, voltage level and short circuit analysis, protection coordination, dynamic and harmonic simulation, Electromagnetic Transient (EMT) analysis and many more [18]. As a result of reviews and negotiations with ÇORUH EDAŞ, it has been detected that faults frequently occur on Akyazı-Düzköy feeder, therefore it is appropriate to use this feeder in this study.

Akyazı TM is a substation which provides energy by reducing the line voltage of 154kV to 31.5kV with a 100MVA transformer. From the Akyazı Distribution Center (DM); Trabzon Fideri1, Trabzon Fideri2, Trabzon Fideri3, Düzköy fideri, Akçaabat Fideri and Söğütlü fideri, a total of 6 feeder exits. Akyazı-Düzköy feeder first enters the Uğurlu DM and then the Kayalar Kök and then energy is distributed to related units. This feeder contains 465 lines, 243 loads, 233 transformers and 1093 busbars. The model parameters are provided by ÇORUH EDAŞ. Using the provided data, Akyaz-Düzköy feeder was modeled as in Figure 1.



(a)



(b)

Figure 1. Model of Akyazı-Düzköy Feeder

2.1.1. Load flow analysis

The Load flow is a numerical steady-state analysis to ensure that the network is operating in the best possible way and to foresee if the system can handle any future problems by pre-planning. Load flow analysis of the feeder modeled in Digsilent Powerfactory program is carried out to see how close the model is to reality by using daily load flow values of Akyazı-Düzköy feeder provided by ÇORUH EDAŞ and shown in Figure 2.

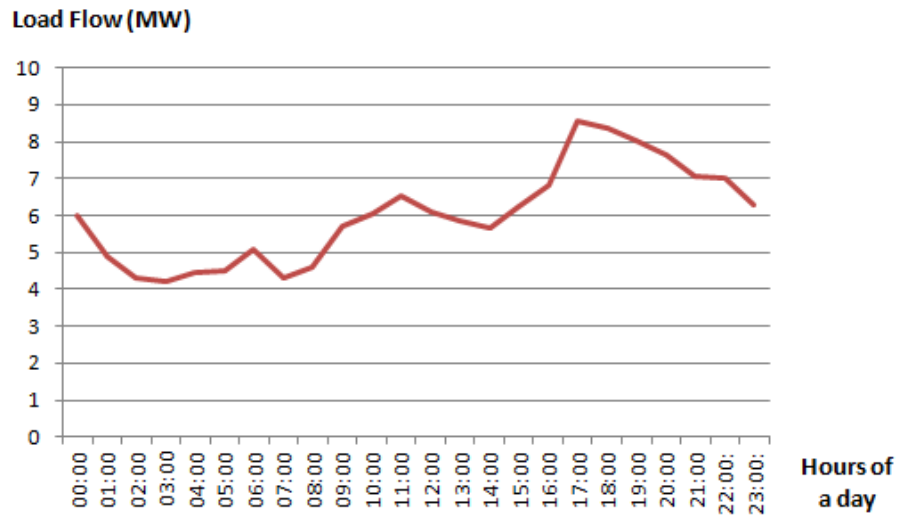


Figure 2. Daily load flow values of Akyazı-Düzköy feeder

3 different hours of the day are selected from the above figure for the analysis;

- 5,083 MW at 06:00
- 6,526 MW at 11:00
- 7,624 MW at 20:00

According to the chosen hours and load values, the load scaling amounts are determined and the analysis of selected busbars are carried out.

In the 1st case, the load scaling amount is determined as 0.165 for 5,083 MW at 06:00 and the voltage values of selected busbars are given in Table 1.

Table 1. The load flow analysis for 0.165 scaling amount

Selected Points	Voltage(kV)	Voltage(p.u., per unit)
Acısu Kök	31,7	1,01
Karacakaya Kök	31,6	1
Doğanköy Kök	31,5	1
Merkez Beton Köşk	31,4	1
Işıklar Kök	31,4	1
Düzköy Kök	31,4	1
Çiğdemli Kök	31,3	0,99
Miran Kök	31,3	0,99
Baykuş Kök	31,3	0,99

In the second case, the load scaling amount for the 6,526 MW at 11:00 is determined as 0,212 and the voltage values of selected busbars are given in Table 2.

Table 2. voltage values for scaling amount of 0.212

Selected Points	Voltage(kV)	Voltage(p.u., per unit)
Acısu Kök	31,4	1
Karacakaya Kök	31,2	0,99
Doğanköy Kök	31,1	0,99
Merkez Beton Köşk	31	0,98
Işıklar Kök	31	0,98
Düzköy Kök	31	0,98
Çiğdemli Kök	30,90	0,98
Miran Kök	30,8	0,98
Baykuş Kök	30,9	0,98

In the 3rd case, the load scaling amount for the 7,624 MW is set to 0.245 at 20:00 and the voltage values of selected busbars are given in Table 3.

Table 3. Voltage result for 0.245 scaling amount

Selected Points	Voltage(kV)	Voltage(p.u., per unit)
Acısu Kök	31,3	0,99
Karacakaya Kök	31	0,98
Doğanköy Kök	30,9	0,98
Merkez Beton Köşk	30,7	0,97
Işıklar Kök	30,7	0,98
Düzköy Kök	30,7	0,97
Çiğdemli Kök	30,60	0,97
Miran Kök	30,5	0,97
Baykuş Kök	30,6	0,97

2.1.2. Short Circuit analysis

Faults in the power system reduce the insulation power of the conductors and damage the system. The causes of these faults can be listed as; lightning, severe winds, natural elements such as earthquakes, aircraft crashes and so on.

It is possible to comment on the fault just by looking at the current and voltage signals obtained from the Digsilent model. Figure 3 shows the 3 phase current-voltage signals when a fault occurs on line H432. Considering the voltage signals given in Figure 3, a significant decrease in phase a and a small decrease in phases b-c can be seen. When the current signals are considered, a significant increase is observed in phase a. If the signals are examined and the theoretical background is taken into consideration, it is possible to determine what kind of fault occurred in the line. It is expected that the voltage value in the phase where the short circuit occurs will decrease while the value of the drawn current in the same phase is reduced, so it is possible to foresee that the fault occurring in the signals indicated in Figure 3 is a single-phase ground fault and this fault occurs in phase a.

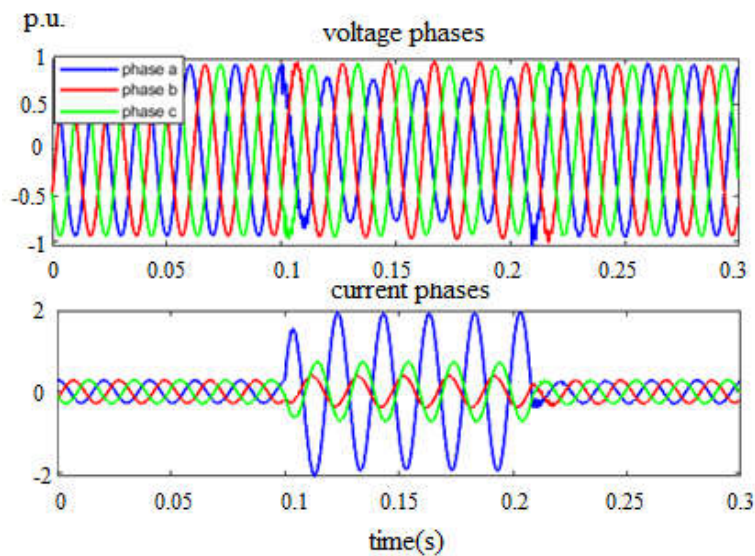


Figure 3. Voltage and current signals for a single-phase ground fault

3. FAULT DETECTION AND CLASSIFICATION ALGORITHM

In the algorithm, firstly wavelet transform is applied to the current data obtained from the modeled feeder. Then, the existence of fault is detected. At this stage, each phase signal is examined at half-period intervals to see if the amplitude change exceeds the specified threshold. The point at which the threshold is exceeded is determined as the inception point of the fault. "No fault" warning is given if the threshold value is not exceeded in any phase. If the fault is present, the energy value of each phase signal is found in order to determine the fault type. Whether the fault is grounded or not is discovered with the mode 0 data obtained from Clarke transform. If the value of mode 0 is too low, there is no grounding.

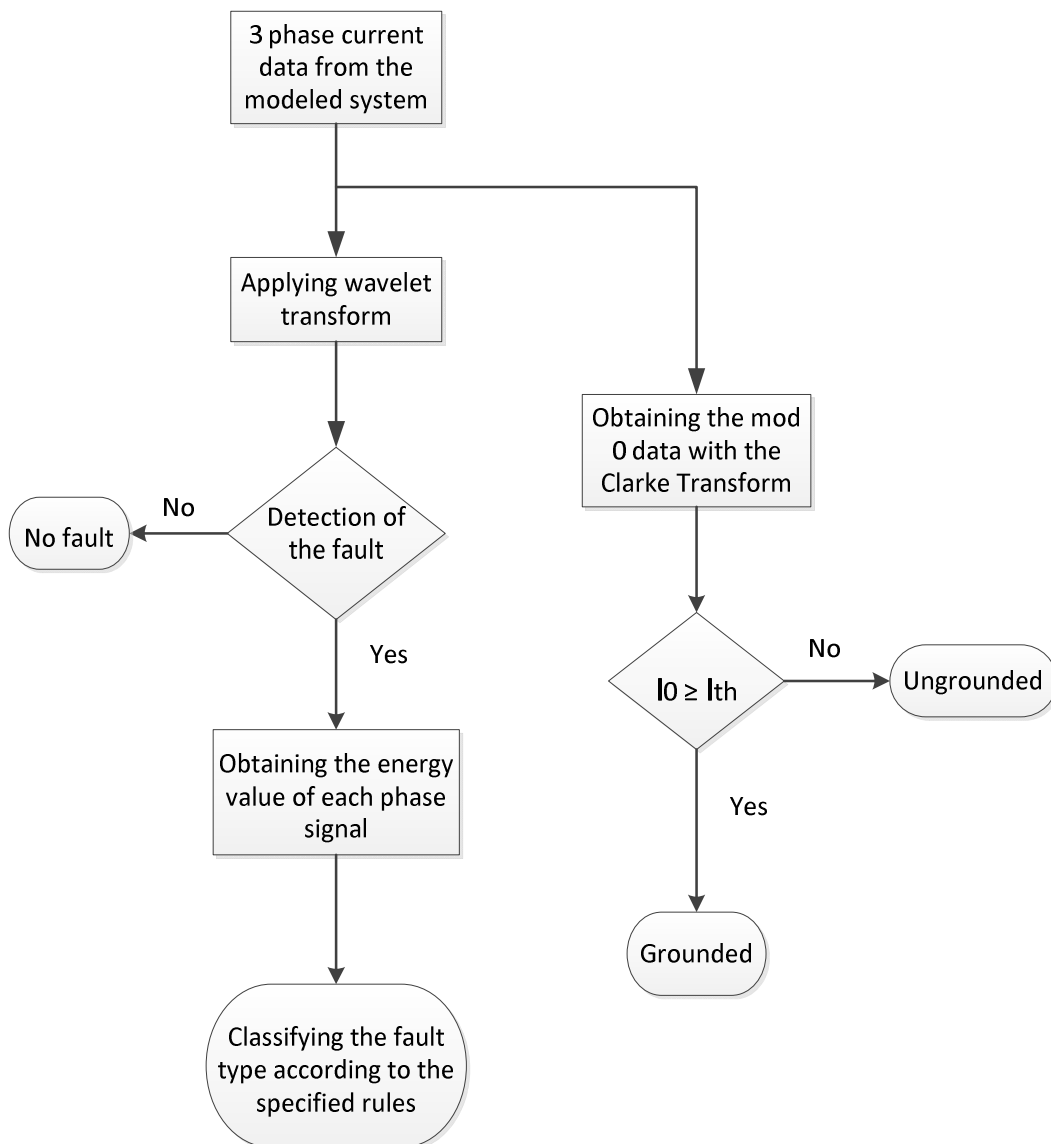


Figure 4. Flowchart of the algorithm

3.1. Wavelet Transform

The Wavelet Transform is a feature extraction method widely used in the literature. The advantage of this method is that it has both time and frequency components and it ensures narrow windows for high frequencies, large windows for low frequencies helping the entire frequency range to be examined.

In this study, the continuous wavelet transform (CWT) coefficients are used and are obtained as in (1).

$$CWT(x, y) = x^{-1/2} \int_{-\infty}^{+\infty} Y(t) \psi \left(\frac{t-x}{y} \right) dt \quad (1)$$

$Y(t)$ represents the sign itself, $\psi(t)$ represents the wavelet function, x and y represents the scale and step magnitude respectively.

3.2. The Energy of the Wavelet Coefficients

After extracting the wavelet coefficient of each current phase signals, it is possible to detect the faulty phase by obtaining the energy values of the current signals as shown in Eq. (2)

$$E = \sum_{n=1}^N [x(n)]^2 \tag{2}$$

where $x(n)$ is the n -th wavelet coefficient of the raw current phase signal, N is the total number of coefficients.

When the energy signals given in Figure 5 are taken into consideration, it can be seen that the energy value of the faulty phase is high and in the faultless phase this value is low.

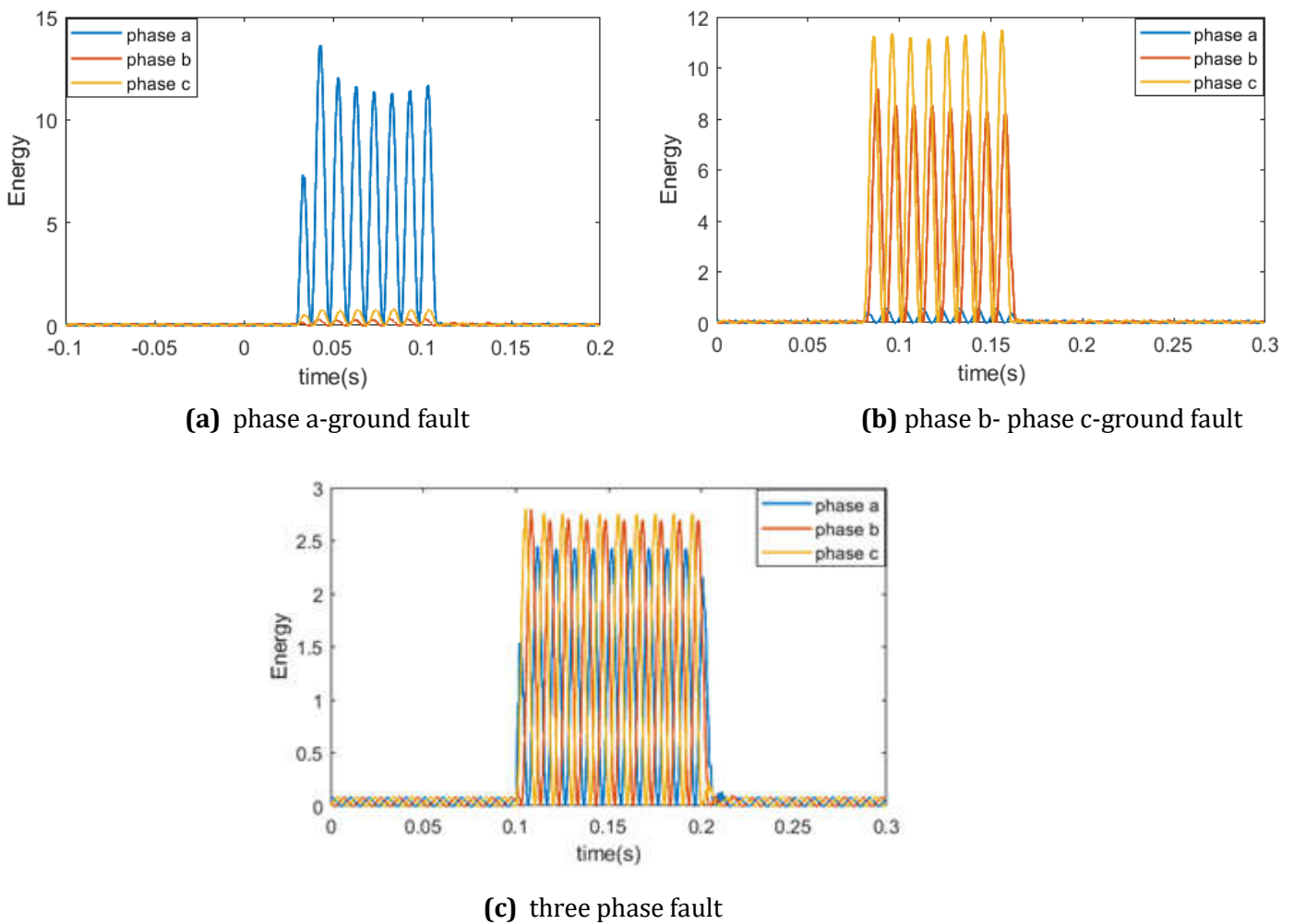


Figure 5. Energy signals for different fault types

3.3. Clarke Transformation

In three-phase systems, the current and voltage waves do not have a constant speed due to the strong electromagnetic effect between the conductors. In literature, **modal transformation** matrices of **Clarke, Wedepohl and Karrenbauer** are frequently used to obtain a constant wave velocity. 3-phase current signals can be transformed into modal components, as in (3) by Clarke's transformation matrix [19].

$$\begin{bmatrix} I_0 \\ I_\alpha \\ I_\beta \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ 0 & \frac{\sqrt{3}}{3} & \frac{\sqrt{3}}{3} \end{bmatrix} \begin{bmatrix} I_a \\ I_b \\ I_c \end{bmatrix} \quad (3)$$

There are 3 modes in total; **mode 0 (ground mode), mode α and mode β (ariel mods)**. Due to the excess of information contained in the signal, mode α and mode β are highly preferred when finding the fault location. Whereas, mode 0 only gets value when there are ground faults, so it can be used to determine the fault type. In (3); I_a, I_b, I_c represent the three-phase current signals while I_0, I_α, I_β represent the ground mode, α mode and β mode of the transformed phase current signals respectively.

In Figure 6, the ground modes of current signals belonging to two different fault type are illustrated. While the ground mode signal of single-phase ground fault shows great changes, the two-phase fault mod 0 signal shows little changes when faults occur between 0.15-0.25 seconds.

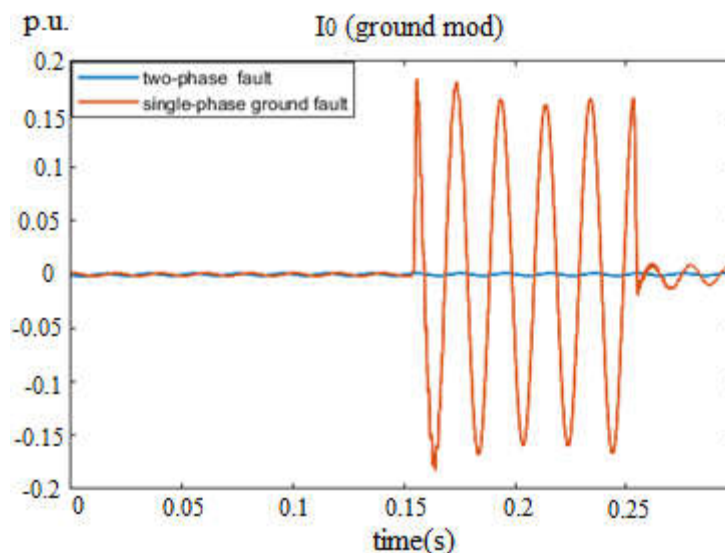


Figure 6. Ground mod signals for different fault types

4. RESULTS

For the validation of the algorithm, different types of faults located in different lines are created on Akyzı-Düzköy feeder model. The simulations are carried out in Digsilent Power Factory (EMT simulations) with a 1 kHz sampling frequency. Faults are applied at different inception times during a 300 ms simulation each. The signals are transported to MATLAB and the performance of the algorithm is tested here.

Table 4 presents the results for different types of faults with different fault impedances. Faults generated on the feeder have been formed on different lines and the efficiency of the algorithm on the general distribution feeder has been investigated.

Table 4. Result for fault type detection

Fault type	Fault resistance(Ω)	Fault location	Detected fault type
AG	5	H26	AG
BC		H216	BC
ACG		H313	ACG
ABC		H410	ABC
AG	15	H26	AG
BC		H216	BC
ACG		H313	ACG
ABC		H410	ABC
AG	30	H26	AG
BC		H216	BC
ACG		H313	AC
ABC		H410	ABC
AG	40	H26	AG
BC		H216	BC
ACG		H313	AC
ABC		H410	ABC

In Table 5, the effectiveness of the algorithm on finding the correct inception time of faults in different locations and types is investigated. When the results are examined, it is seen that in some values of inception time the algorithm is operating perfectly while in other inception time values it is not. The reason for this is mostly the size of the window used to determine whether the fault exists or not. Based on the results it can be said that the algorithm will give a maximum time delay of 9 ms.

Table 5. Result for detection of inception time

Fault type	Fault resistance(Ω)	Fault location	Fault inception time(s)	Time Delay(s)
AG	5	H26	0.18	0
BC		H216	0.08	0
ACG		H313	0.122	0.002
ABC		H410	0.155	0.005
AG	15	H26	0.18	0
BC		H216	0.08	0
ACG		H313	0.122	0.002
ABC		H410	0.155	0.005
AG	30	H26	0.18	0
BC		H216	0.08	0
ACG		H313	0.122	0.002
ABC		H410	0.155	0.005
AG	40	H26	0.18	0
BC		H216	0.08	0
ACG		H313	0.122	0.002
ABC		H410	0.155	0.005

As mentioned before, the fault detection and classification is carried out with the energy values of each phase signal and the current ground mod value. In Table 6, the obtained energy and ground mod values are clearly viewed regarding the fault types. As an example, the energy values of each phase are 3.754, 0.107, 0.193 respectively for AG fault with a 5 fault resistance located on line H26. From these values, it is obvious that the fault has occurred on phase A. Also with the high I_0 value, it can be said that the fault is ground connected.

Table 6. Phase energy values for different fault conditions

Fault type	Fault resistance(Ω)	Fault location	Energy			Io
			a	b	c	
AG	5	H26	3.754	0.107	0.193	0.347
BC		H216	0.062	2.581	2.456	0.005
ACG		H313	1.537	0.140	1.304	0.102
ABC		H410	0.576	0.631	0.622	0.010
AG	15	H26	1.511	0.088	0.119	0.204
BC		H216	0.062	1.558	1.505	0.004
ACG		H313	0.921	0.126	0.816	0.080
ABC		H410	0.435	0.469	0.492	0.009
AG	30	H26	0.651	0.077	0.089	0.120
BC		H216	0.062	0.875	0.862	0.003
ACG		H313	0.531	0.108	0.502	0.061
ABC		H410	0.313	0.331	0.348	0.008
AG	40	H26	0.454	0.073	0.081	0.095
BC		H216	0.062	0.652	0.650	0.002
ACG		H313	0.407	0.100	0.397	0.051
ABC		H410	0.264	0.277	0.292	0.007

5. CONCLUSION

In this paper, analysis of a real distribution feeder modeled in Digsilent Power Factory is evaluated and a fault detection-classification algorithm is proposed. The proposed method is based on wavelet transform and signal energy combining with Clarke transform to detect the right fault type. The validation of the algorithm is carried out with the model data. The fault inception time and the effect of the fault resistance is also investigated. The results give high accuracy in different conditions.

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